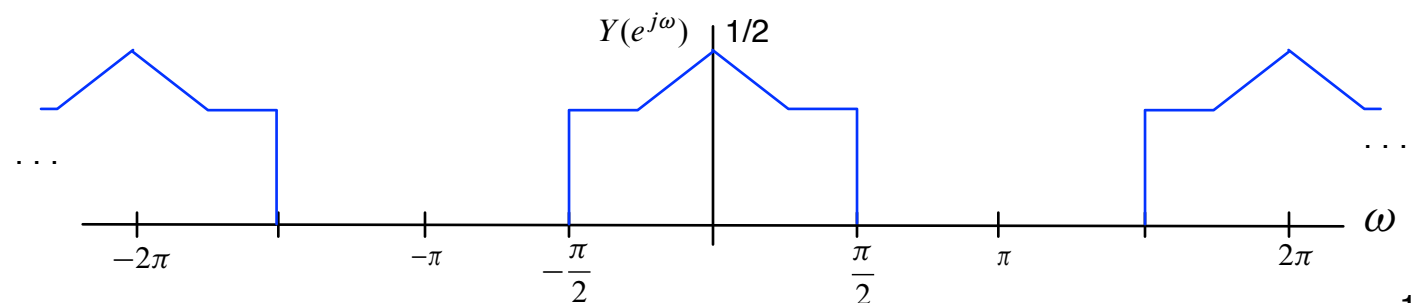
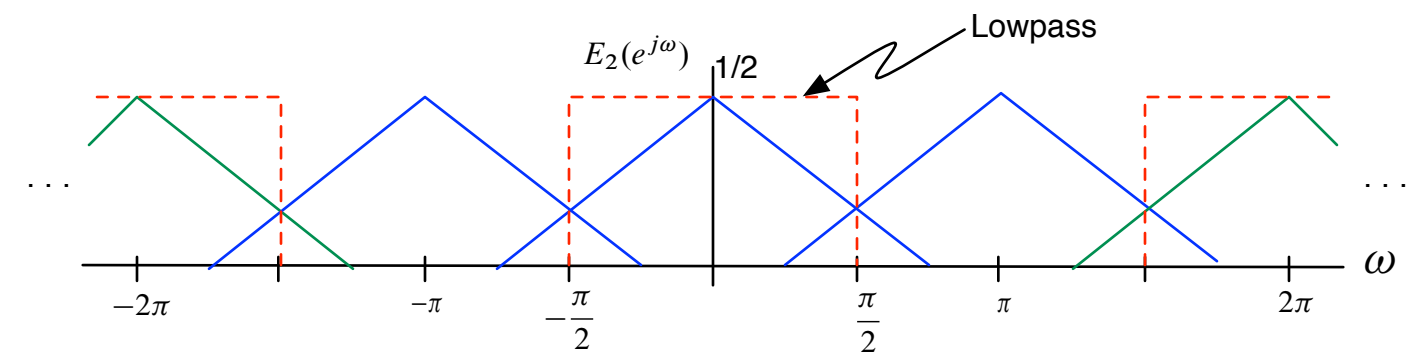
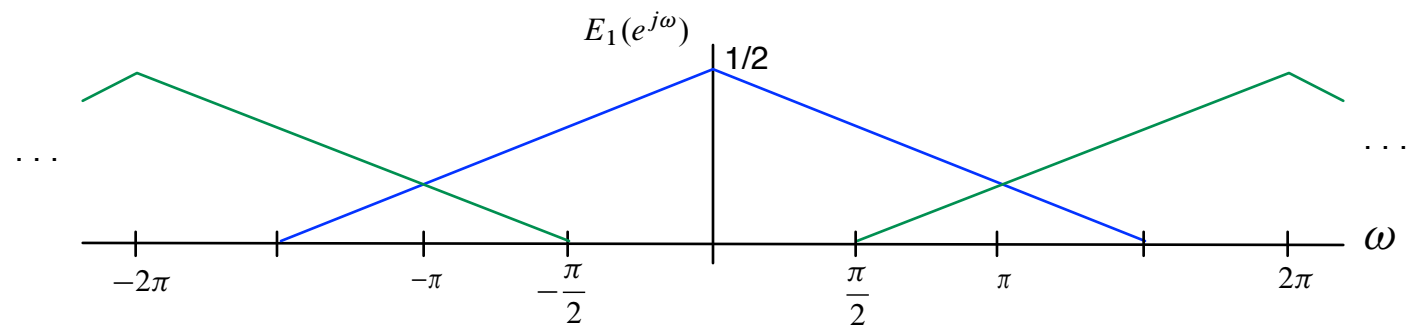
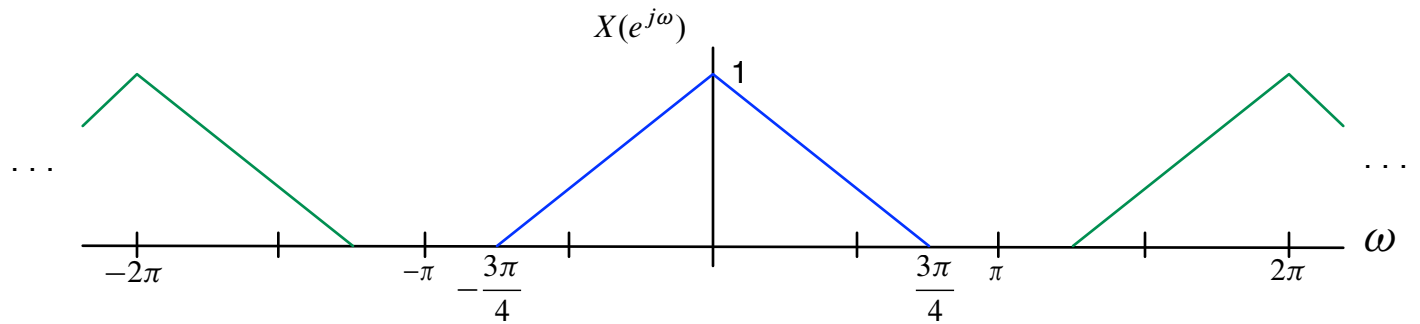
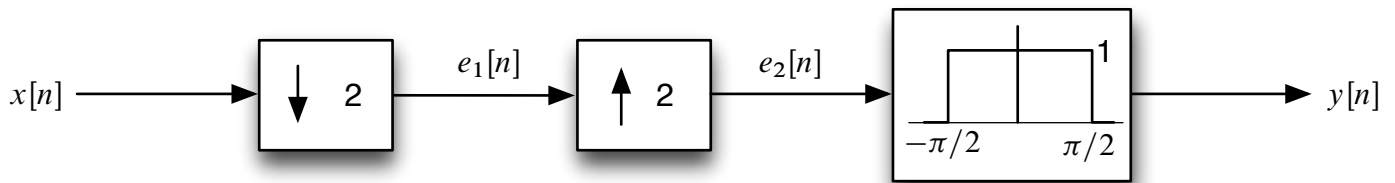
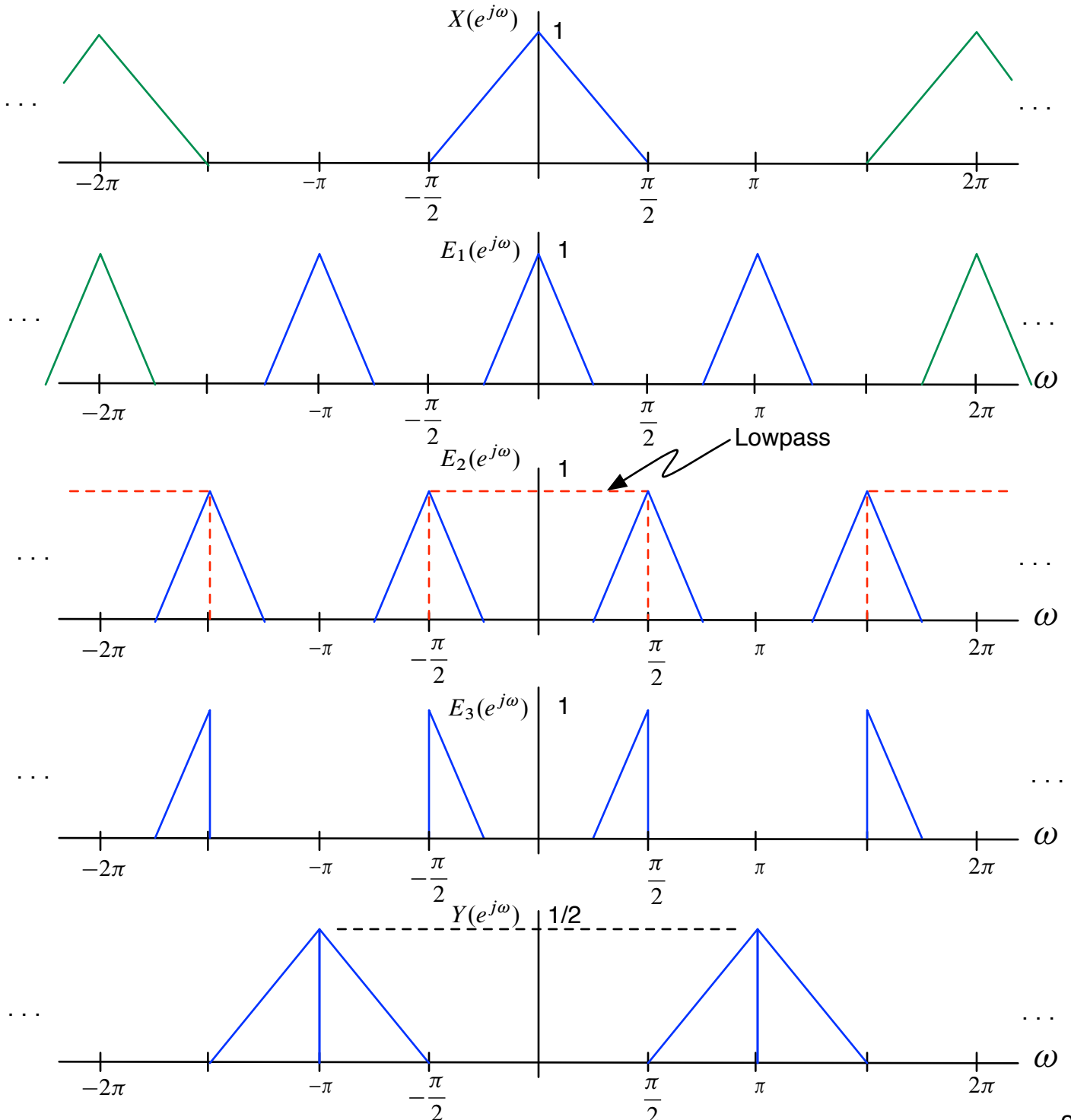
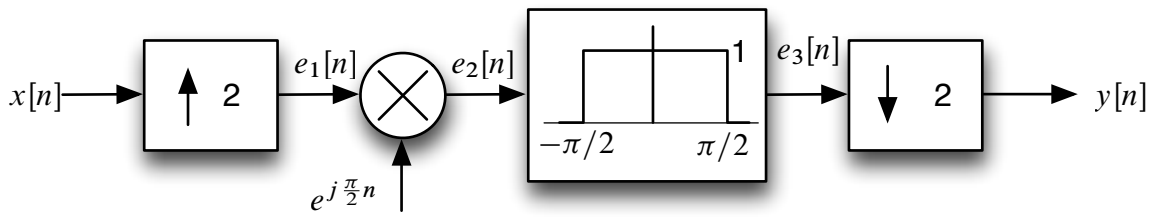


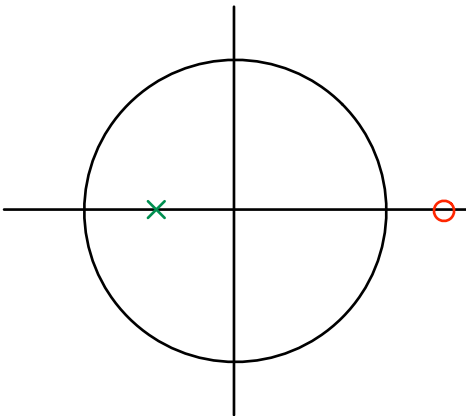
System Model with input $x[n]$ and output $y[n]$



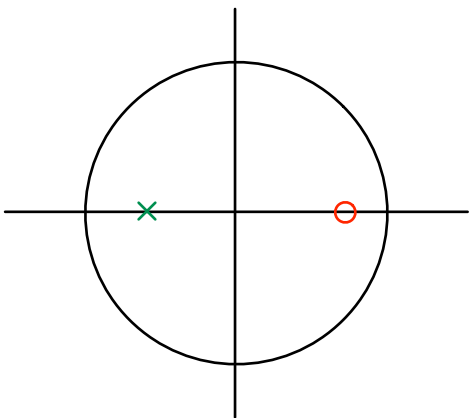
System Model with input $x[n]$ and output $y[n]$



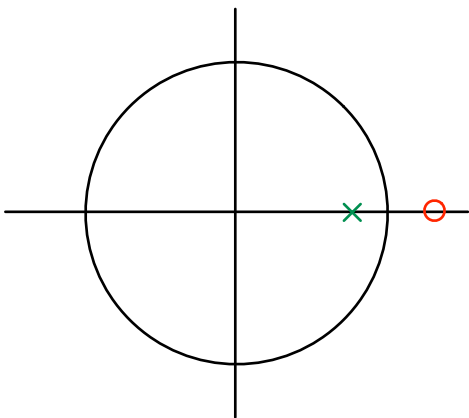
Starting Point $H(z)$



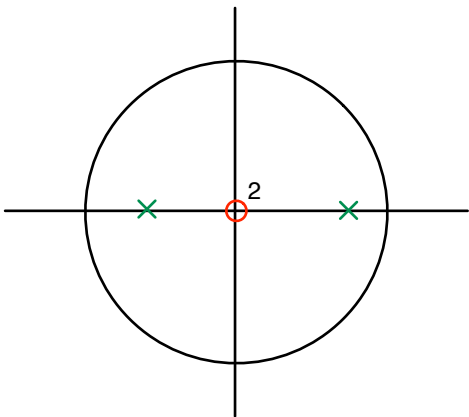
$H_{\min}(z)$



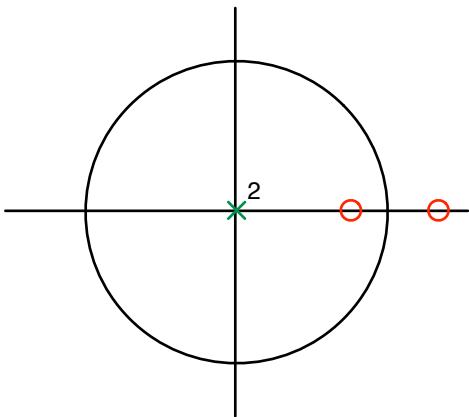
$H_{\text{ap}}(z)$



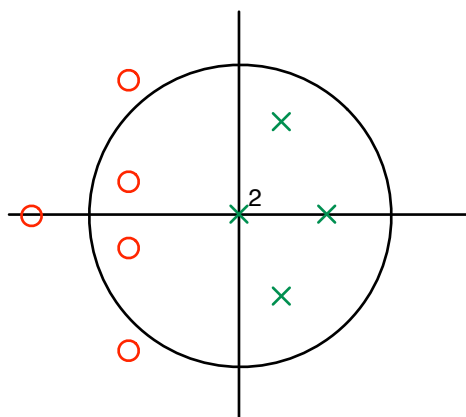
$H_{\min}(z)$



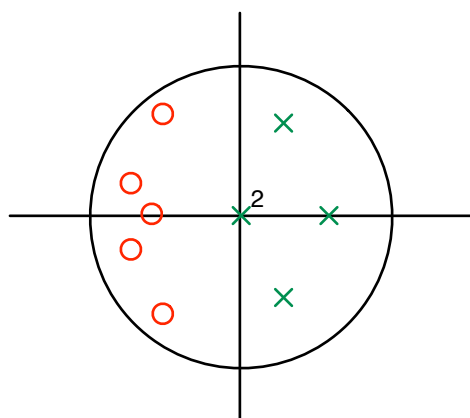
$H_{\text{lin}}(z)$



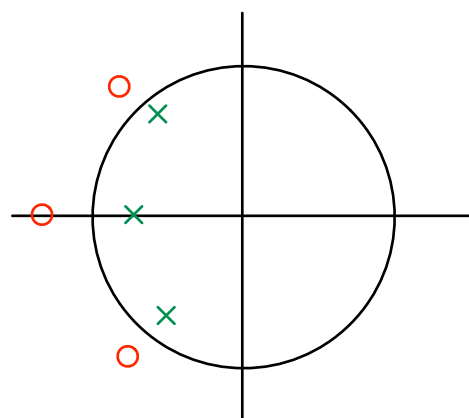
Starting Point $H(z)$



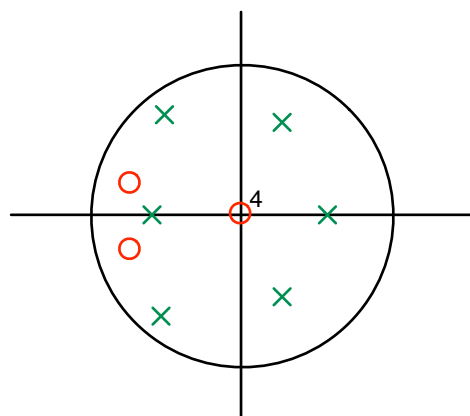
$H_{\min}(z)$



$H_{\text{ap}}(z)$



$H_{\min}(z)$



$H_{\text{lin}}(z)$

